

# CMS DAQ

## Zynq Ultrascale+

### Software Reference Manual

INFN Padova

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The interface consists of a web page that implements a series of forms for setting the operating parameters, access to all the registers of the various chips and a WebSocket Server (RFC 6455) which responds on port 4444.

LabView library to communicate with the server is available

<https://www2.pd.infn.it/~caste/pub/WebSockets.zip>

Also there are the following servers, one for RO data on port 3333, one for TRG data on port 3334, and one for MINICRATE communication on port 28888, primary port use CCB address 0, or if different from 0 use secondary port .

RO link led are on only if channel is enabled and locked, TRG link led are on only if locked, enable are not effect. If internal PLL lose lock all link are reset so if lose lock auto clear is enabled and lock is lost for 1 second the delay is automatically restored to the last value to try restore link lock.

Spare IO definition

IN\_NIM1 is TTC input, must be selected by command

IN\_NIM2 is L1A input, must be selected by command

IN\_NIM3 is EXT1 TRIG input

IN\_NIM4 is EXT2 TRIG input

OUT\_NIM1 is CLK out

OUT\_NIM2 is TTC out

OUT\_NIM3 is L1A out

OUT\_NIM4 is LHC CLK out

Preliminary commands implemented.

#### Binary commands accepted by server are:

Commands implemented with WebSocket opt code = binary frame.

The format of the frames: [cmd] [arg1] ..... [argn].

The first byte represents the command followed by the arguments.

The following structures describe the arguments for each command, UINT32 represents an integer 32bit (4 bytes) in little-Endian format, FLOAT64 an 8byte floating point in little-Endian format.

**Operation**, code 0x01

Manual operation for data link phase adjust and enable and disable channels. Enable/Disable channel for trigger are :

TRG Channel 0 Global enable trigger;

TRG Channel 1 L1A enable.

TRG Channel 2-7 unused.

BYTE cmd;

BYTE interf; //select interface 0=RO, 1=TRG

BYTE op; //0=dec-delay, 1=inc-delay, 2=inc-pos, 3=clr-lost, 4=enable, 5 disable

BYTE ch; //channel 0-7

**Return** : the status frame, see Status command

#### **Auto Clear, code 0x04**

Activate/disactivate the auto clear lost lock flag.

BYTE cmd;

BYTE interf; //select interface 0=RO, 1=TRG

BYTE ch; //channel 0-7

BYTE value; //value 0-1

**Return** : the same data sent.

#### **Reset lost lock counter, code 0x05**

BYTE cmd;

BYTE interf; //select interface 0=RO, 1=TRG

BYTE ch; //channel 0-7

**Return** : the same data sent..

#### **Set Val and Mask, code 0x03**

BYTE cmd;

BYTE interf; //select interface 0=RO, 1=TRG

INT32 val[4]; //format 0x0BBB0AAA, AAA= 10bit value CH0..... CH7

INT32 mask[4]; //format 0x0BBB0AAA, AAA= 10bit mask CH0..... CH7

**Return** :

BYTE cmd; //0x03

BYTE interf; //select interface 0=RO, 1=TRG

INT32 val[4]; //format 0x0BBB0AAA, AAA= 10bit value CH0..... CH7

```
INT32 mask[4]; //format 0x0BBB0AAA, AAA= 10bit mask CH0..... CH7
INT32 autoclear[8]; //0 or 1 auto clear state
INT32 enable; //channel enabled
```

#### **Get Val and Mask, code 0x83**

```
BYTE cmd;
BYTE interf; //select interface 0=RO, 1=TRG
Return :
BYTE cmd; //0x03
BYTE interf; //select interface 0=RO, 1=TRG
INT32 val[4]; //format 0x0BBB0AAA, AAA= 10bit value CH0..... CH7
INT32 mask[4]; //format 0x0BBB0AAA, AAA= 10bit mask CH0..... CH7
INT32 autoclear[8]; //0 or 1 auto clear
INT32 enable; //channel enabled
```

#### **Trigger Previous words, code 0x08**

Set the number of word saved in the FIFO before the trigger.

```
BYTE cmd;
BYTE val; //number of word saved in the FIFO before trigger
Return :
BYTE cmd; //0x0E
UINT32 cfg; //trigger config. Format: 0xFOSDDAAPP
//PP 8bit number of previous word
//AA 8bit number of after word
//DD 8bit delay
//S 3bit select input trigger
//O 4bit select output signal
//F msbit 1=fall edge, 0=rise edge
```

**Trigger After words**, code 0x09

Set the number of word saved in the FIFO after the trigger.

```
BYTE cmd;  
  
BYTE val;    //number of word saved in the FIFO after the trigger
```

**Return :**

```
BYTE cmd;    //0x0E  
  
UINT32 cfg;  //word trigger config. Format: 0xFOSDDAAPP  
  
            //PP 8bit number of previous word  
  
            //AA 8bit number of after word  
  
            //DD 8bit delay  
  
            //S 3bit select input trigger  
  
            //O 4bit select output signal  
  
            //F msbit 1=fall edge, 0=rise edge
```

**Trigger Delay**, code 0x0A

Set trigger delay to start save word on the FIFO.

```
BYTE cmd;  
  
BYTE val;    //Delay in CLK unit (1/3 BX = 120MHz)  
  
Return :  
  
BYTE cmd;    //0x0E  
  
UINT32 cfg;  //word trigger config. Format: 0xFOSDDAAPP  
  
            //PP 8bit number of previous word  
  
            //AA 8bit number of after word  
  
            //DD 8bit delay  
  
            //S 3bit select input trigger  
  
            //O 4bit select output signal  
  
            //F msbit 1=fall edge, 0=rise edge
```

### Select input Trigger, code 0x0B

Set input trigger.

```
BYTE cmd;  
  
BYTE val;    //0=TRGOUT, 1=CALup, 2=CCB_RDYup, 3=CALdw, 4=CCB_RDYdw, 5=trigger(0),  
             6=trigger(1), 7=random trigger generator
```

#### Return :

```
BYTE cmd;    //0x0E  
  
UINT32 cfg;  //word trigger config. Format: 0xFOSDDAAPP  
  
            //PP 8bit number of previous word  
  
            //AA 8bit number of after word  
  
            //DD 8bit delay  
  
            //S 3bit select input trigger  
  
            //O 4bit select output signal  
  
            //F msbit 1=fall edge, 0=rise edge
```

### Select output L1A, code 0x25

Select signal output on LEMO L1A.

```
BYTE cmd;  
  
BYTE val;    //0=L1A 1=TRGOUT, 2=CALup, 3=CCB_RDYup, 4=CALdw, 5=CCB_RDYdw,  
             6=trigger(0), 7=trigger(1), 8=random trigger generator
```

#### Return :

```
BYTE cmd;    //0x0E  
  
UINT32 cfg;  //word trigger config. Format: 0xFOSDDAAPP  
  
            //PP 8bit number of previous word  
  
            //AA 8bit number of after word  
  
            //DD 8bit delay  
  
            //S 3bit select input trigger  
  
            //O 4bit select output signal  
  
            //F msbit 1=fall edge, 0=rise edge
```

### Rate Random Trigger Generator, code 0x24

Set input trigger.

```
BYTE cmd;  
  
BYTE val;    // rate = (2^val) * 25ns / 2  
  
Return :  
  
BYTE cmd;    //0x24  
  
BYTE val;
```

### Read Rate Random Trigger Generator, code 0xA4

Set input trigger.

```
BYTE cmd;  
  
Return :  
  
BYTE cmd;    //0x24  
  
BYTE val;    // rate = (2^val) * 25ns / 2
```

### Set edge Trigger, code 0x14

Set input trigger edge.

```
BYTE cmd;  
  
BYTE val;    //1=fall edge, 0= ris edge  
  
Return :  
  
BYTE cmd;    //0x0E  
  
UINT32 cfg;  //word trigger config. Format: 0xFOSDDAAPP  
  
            //PP 8bit number of previous word  
  
            //AA 8bit number of after word  
  
            //DD 8bit delay  
  
            //S 3bit select input trigger  
  
            //O 4bit select output signal  
  
            //F msbit 1=fall edge, 0=rise edge
```

**TTC Orbit**, code 0x0C

Set TTC orbit

```
BYTE cmd;  
  
BYTE val;    //BX orbit = (val+1)*44; LHC = 3564 bx  
  
Return :  
  
BYTE cmd;    //0x0F  
  
UINT32 cfg;  //word trigger config. Format: 0x0000EE00  
  
              //OO 8bit number orbit/44  
  
              //EE 1bit enable
```

**TTC Orbit enable**, code 0x0D

Set TTC orbit enable

```
BYTE cmd;  
  
BYTE val;    //ON/OFF  
  
Return :  
  
BYTE cmd;    //0x0F  
  
UINT32 cfg;  //word trigger config. Format: 0x0000EE00  
  
              // OO 8bit number orbit/44  
  
              //EE 1bit enable
```

**CFG read**, code 0x90

```
BYTE cmd;  
  
BYTE interf;  //0=RO, 1=TRG  
  
Return :  
  
BYTE cmd;    //0x10  
  
BYTE interf;  //0=RO, 1=TRG  
  
UINT32 cfg;  //word interface config. Format: 0x0000EE00 for RO and 0xFOSDDAAPP  
  
              //for trigger
```

```
UINT32 cfg1; //RO 0x0000MDD. DD L1A delay, M bit0=TTInput Mbit2=L1Ainput
           //TRG dead time
UINT32 cfg2; // RO not used
           // TRG num trigger
```

**Dead time , code 0x15**

```
BYTE cmd;
UINT32 dead; //trigger dead time in clk of 120MHz
Return :
BYTE cmd; //0x15
UINT32 dead; //trigger dead time in clk of 120MHz
```

**Set Number of Trigger , code 0x16**

```
BYTE cmd;
UINT32 numtrg; //0=trigger counter disabled, the number of trigger to acquire, use TRB
               Disable/Enable bit 0 to rearm counter
Return :
BYTE cmd; //0x16
UINT32 numtrg; //the number of trigger to acquire
```

**Read Dead time , code 0x95**

```
BYTE cmd;
Return :
BYTE cmd; //0x15
UINT32 dead; //trigger dead time in clk of 120MHz
```

**Read Number of Trigger , code 0x96**

```
BYTE cmd;
Return :
BYTE cmd; //0x16
UINT32 numtrg; //the number of trigger to acquire
```

**Set L1A delay , code 0x19**



```
BYTE cmd;  
BYTE delay;          //num clock (40MHz) delay
```

**Return :**

```
BYTE cmd;    //0x19  
BYTE delay;  //delay
```

**Use TTC input , code 0x1A**

```
BYTE cmd;  
BYTE input;          //1= use NIM1 input as TTC optic
```

**Return :**

```
BYTE cmd;    //0x1A  
BYTE input;  // input
```

**Read Use TTC input , code 0x9A**

```
BYTE cmd;  
  
Return :  
  
BYTE cmd;    //0x1A  
BYTE input;  // TTC input
```

**Use L1A input , code 0x1B**

```
BYTE cmd;  
BYTE input;          //1= use NIM2 input as L1A to TTC
```

**Return :**

```
BYTE cmd;    //0x1B  
BYTE input;  // input
```

**Read Use L1A input , code 0x9B**

```
BYTE cmd;  
  
Return :  
  
BYTE cmd;    //0x1B  
BYTE input;  // L1A input
```

**TTC broadcast**, code 0x11

Set TTC broadcast cmd

```
BYTE cmd;  
  
BYTE val;    //TTC broadcast value
```

**Return :**

```
BYTE cmd;    //0x11  
  
BYTE val;    //TTC broadcast value
```

**Link scan**, code 0x06

Find and set delay for the data link

```
BYTE cmd;  
  
BYTE interf; //select interface 0=RO, 1=TRG
```

**Return :**

```
0x07,<byte Interface>,<uint32 Totalsize>,  
<uint32 Namesize>,<CString>,  
<uint32 Datasize>,<Data>,  
<uint32 Namesize>,<CString>,  
<uint32 Datasize>,<Data>,  
...  
...  
<uint32 Maxrecord>
```

Interface: the interface number 0=RO 1=TRB

Totalsize: is the size in byte of data transferred, tag 0x07 included, in little Endian format.

Namesize: is the size in byte of the string name that identified the data, end string included (char=0), in little Endian format.

Cstring: is the byte array contained the name of data.

Datasize: is the data size in byte.  
Data: is the vector array. Vector\_0 [x, y], Vector\_1[x, y] .....  
x and y are in double float precision (8 byte) in little Endian format.  
Maxrecord: is the maximum number of vectors return in data.

**Status**, code 0x82

Get the links status, if scanning is running return also scan data frame

```
BYTE cmd;  
BYTE interf; // select interface 0=RO, 1=TRG  
Return :  
BYTE cmd; //0x02  
BYTE interf; //0=RO, 1=TRG  
INT32 spydata[8]; //format 0xLVVVPDDD, L bit 31=Lock, bit 30=LoseLock, VVV 12bit value, P  
4bit position, DDD 12bit delay  
INT32 ber[2]; //0xDDCCBBAA 0xHHGGFFEE, AA=CH0, ....HH=CH7  
INT32 nLose[8]; //the 8 channel counter
```

**LinkAuto**, code 0x12

Tune the Minicrate primary port link

```
BYTE cmd;  
Return :  
BYTE cmd; //0x13  
INT32 offset; // offset  
INT32 ampl; // amplitude
```

**Save**, code 0x17

Save the link delay

```
BYTE cmd;  
Return :  
BYTE cmd; //0x17
```

**Rate, code 0x98**

Read the trigger rate

BYTE cmd;

**Return :**

BYTE cmd; //0x18

INT32 rate; // rate

**Extern Clock, code 0x1C**

Set external clock input

BYTE cmd;

BYTE ext; //1=use external clock input, 0=use internal clock

**Return :**

BYTE cmd; //0x1C

BYTE pllstatus; //0x00 = OK pll locked

**Si5338 PLL status and Xilinx Pll, code 0x9D**

Get Si5338 PLL status

BYTE cmd;

BYTE reset; //reset nLoseLock;

**Return :**

BYTE cmd; //0x1D

BYTE pllstatus; //0x00 = OK pll locked

INT32 nLoseLock; // Lose lock number

BYTE xpllstatus; //Xilinx pll, bit0 = lose lock, bit1= locked. lose lock automatically clear

**Temperature, code 0x9E**

Get temperature sensors

BYTE cmd;

**Return :**

```
BYTE cmd; //0x1E
FLOAT32 pl; //Programmable Logic Temperature
FLOAT32 ps; //Processor System Temperature
FLOAT32 rem; //Remote Temperature
FLOAT32 phy; //Ethernet PHY Temperature
INT32 numsensor; //number of external sensors

INT32 id_L; // external sensor code ID lsb
INT32 id_H; // external sensor code ID msb
FLOAT32 t; // Temperature
.
.
INT32 id_L; // external sensor code ID lsb
INT32 id_H; // external sensor code ID msb
FLOAT32 t; // Temperature
```

**Find Temperature Sensor, code 0x9F**

```
BYTE cmd;

Return :

BYTE cmd; //0x1F

INT32 numsensor; //number of external sensors

INT32 id_L; // external sensor code ID lsb
INT32 id_H; // external sensor code ID msb
.
.
INT32 id_L; // external sensor code ID lsb
INT32 id_H; // external sensor code ID msb
```

**I2C, code 0x20**

```
BYTE cmd;  
BYTE data;  
BYTE ctrl;    bit0=start, bit1=stop, bit2=read, bit3=ackn, bit4=abort. Bit3 and 4 are ignored  
.  
.  
BYTE data;  
BYTE ctrl;  
Return :  
BYTE cmd;    //0x20  
BYTE data;  
BYTE err;  
.  
.  
BYTE data;  
BYTE err;
```

**Max in DDR Buffer, code 0xA1**

```
BYTE cmd;  
BYTE interf;  // select interface 0=RO, 1=TRG  
Return :  
BYTE cmd;    //0x21  
BYTE interf;  // select interface 0=RO, 1=TRG  
INT32 size;  // maximum size reached by the DDR buffer since the last reading
```

**RO rate**, code 0xA2

BYTE cmd;

**Return :**

BYTE cmd; //0x22

INT32 rate; // RO data rate in byte

**TP Generator**, code 0x23

BYTE cmd;

INT32 TPrate; //TP rate in milliseconds

INT32 TPnum; //numbers of Test Pulse

INT32 ADVnum; //numbers of sequence Advance

**Return :**

BYTE cmd; //0x23

INT32 TPrate; //TP rate in milliseconds

INT32 TPnum; //numbers of Test Pulse

INT32 ADVnum; //numbers of sequence Advance

**Return data on error** , code 0xFF:

BYTE cmd; //0xFF

INT32 errorcode; // Error code

**Error code:**

-1 Not Authorized

-22 Invalid Value

-5 I/O Error

-9 Unknow command (connection will be closed)

-2 no such file

-13 Permission denied

-16 Busy

See linux c/c++ error base for undefined number (errno-base.h)

**TEXT commands accepted by server are:**

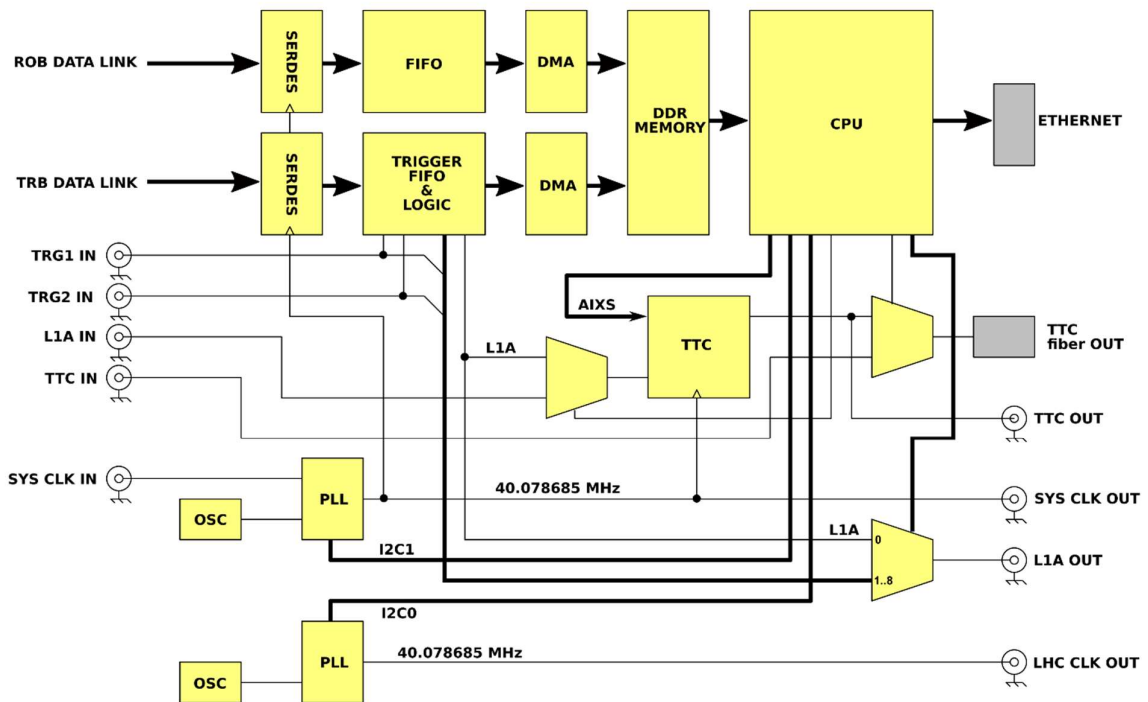
<b>Temperature?</b>	Return the temperature
<b>FindSensor?</b>	Find external sensor and return the sensor id code
<b>Rate?</b>	Return the L1A rate
<b>RORate?</b>	Return the RO data rate in byte
<b>Version?</b>	Return the App version string
<b>Save</b>	Save link delay
<b>Async</b>	Set async data mode for scan waveform
<b>notAsync</b>	Disable async data mode (no data return at end of scan).
<b>Inclstep:&lt;inc&gt;</b>	inc=0 decrement internal frequency 1ppm, inc=1 increment frequency 1ppm
<b>Extclkstep:&lt;inc&gt;</b>	inc=0 decrement external frequency 1ppm, inc=1 increment frequency 1ppm
<b>Inclkreset</b>	reset internal frequency to default value.
<b>Extclkreset</b>	reset extern frequency to default value.







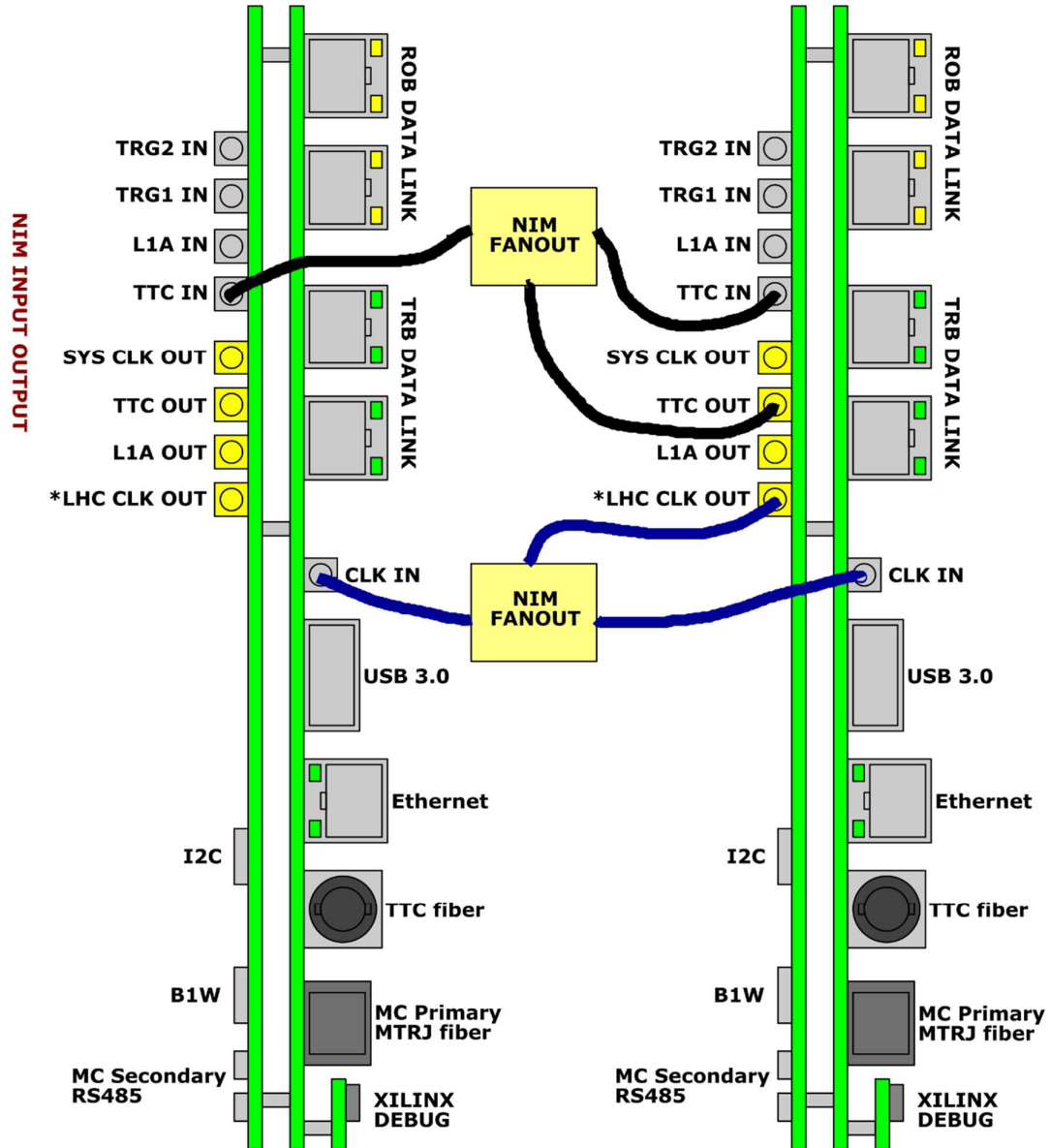
# CMS DAQ Zynq Ultrascale+ BLOCK DIAGRAM



# CMS DAQ Zynq Ultrascale+

**SLAVE**

**SLAVE**



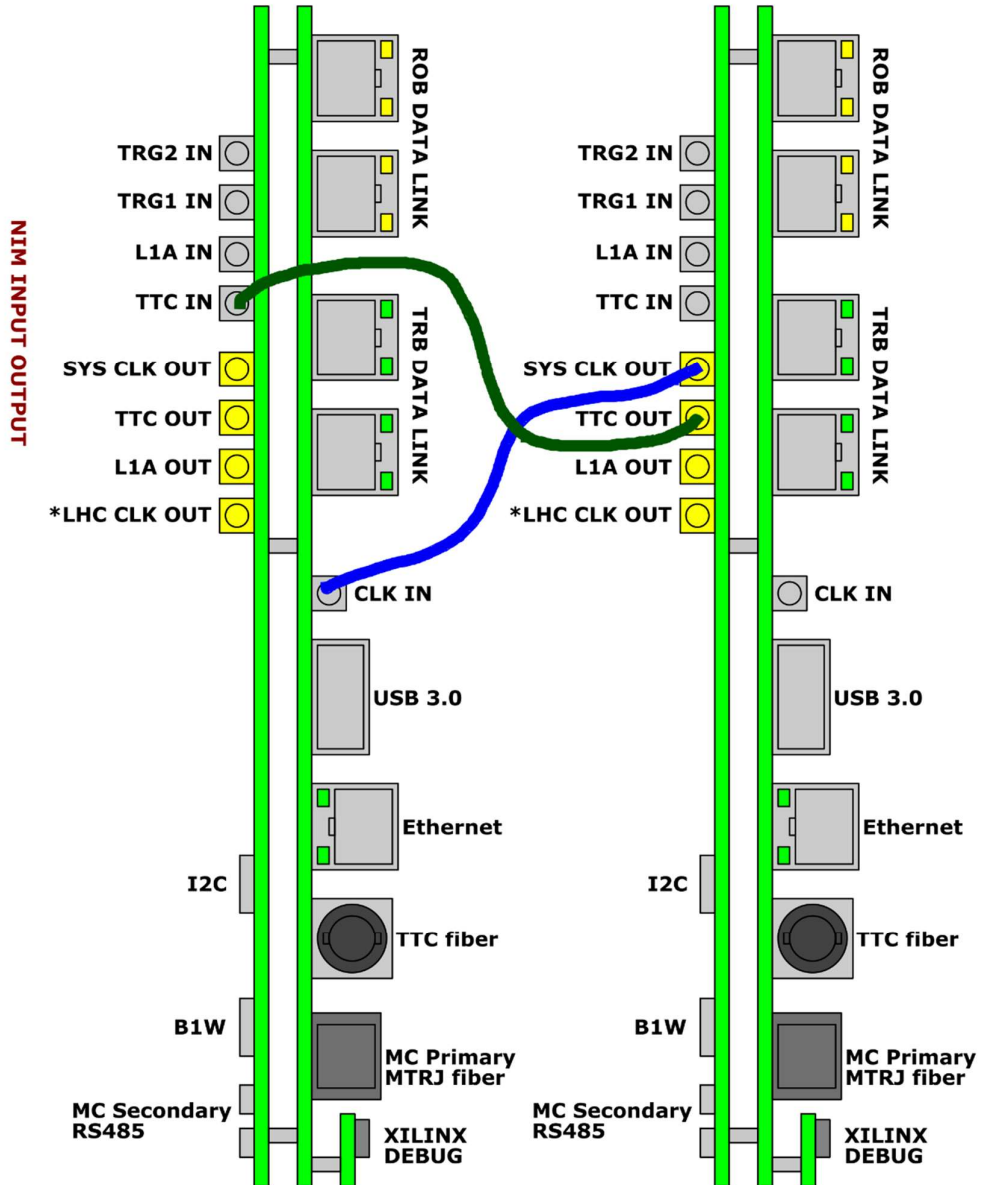
Slave cmd:  
 0x1C 0x01 (use external CLK)  
 0x1A 0x01 (use NIM input  
 for TTC fibert out)

\* CLK indipendente da usare con un fanout per poi collegarlo al CLK IN di piu schede

# CMS DAQ Zynq Ultrascale+

## SLAVE

## MASTER



Slave cmd:  
 0x1C 0x01 (use external CLK)  
 0x1A 0x01 (use NIM input  
 for TTC fibert out)

Master cmd:  
 0x1C 0x00 (use internal CLK)  
 0x1A 0x00 (use internal TTC  
 for fibert out)

\* CLK indipendente da usare con un fanout  
 per poi collegarlo al CLK IN di piu schede